

## 20ME2702A - MECHATRONICS

<b>Offering Branches</b>	ME		
<b>Course Category:</b>	Open Elective -IV	<b>Credits:</b>	3
<b>Course Type:</b>	Theory	<b>Lecture-Tutorial-Practical:</b>	3-0-0
<b>Prerequisites:</b>	20ES1101 - Basic electrical and electronics engineering	<b>Continuous Evaluation:</b>	30
		<b>Semester End Evaluation:</b>	70
		<b>Total Marks:</b>	100

### Course Outcomes

Upon successful completion of the course, the student will be able to:

<b>CO1</b>	<b>Explain</b> the concepts related to elements of Mechatronic systems.	<b>K2</b>
<b>CO2</b>	<b>Summarize</b> the construction and working of sensors used in building mechatronic systems.	<b>K3</b>
<b>CO3</b>	<b>Illustrate</b> various types of actuation systems and their components.	<b>K3</b>
<b>CO4</b>	<b>Develop</b> mathematical models using building blocks and make use of these models to find the dynamic response.	<b>K3</b>
<b>CO5</b>	<b>Summarize</b> the construction and working of closed loop controllers, Micro processor and Micro controllers.	<b>K3</b>
<b>CO6</b>	<b>Illustrate</b> the features and applications of digital logic, PLC and of Fuzzy logic.	<b>K3</b>

### Contribution of Course Outcomes towards achievement of Program Outcomes

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
<b>CO1</b>	3									2		2	3	1
<b>CO2</b>	3									2		2	3	1
<b>CO3</b>	3		3							2		2	3	1
<b>CO4</b>	3	3			2					2		2	3	1
<b>CO5</b>	3				2					2		2	3	1
<b>CO6</b>	3				2					2		2	3	1
<b>Avg.</b>	<b>3</b>	<b>3</b>	<b>3</b>		<b>2</b>					<b>2</b>		<b>2</b>	<b>3</b>	<b>1</b>

**1- Low**

**2-Medium**

**3-High**

### Course Content

<b>UNIT-1</b>	<p><b>INTRODUCTION:</b> Definition of Mechatronics, evolution of mechatronics, systems, measurement systems, control systems, mechatronic design process, traditional design and mechatronic design, applications of mechatronic systems, advantages and disadvantages of mechatronic systems.</p> <p><b>SENSORS:</b> classification of sensors, basic working principles, Velocity sensors – Proximity and Range sensors, ultrasonic sensor, laser interferometer transducer, Hall Effect sensor, inductive proximity switch. Light sensors – Photodiodes, phototransistors, tactile sensors – PVDF tactile sensor, micro-switch and reed switch, Piezoelectric sensors, vision sensor</p>	<b>CO1</b> <b>CO2</b>
<b>UNIT-2</b>	<p><b>PNEUMATIC AND HYDRAULIC ACTUATION SYSTEMS:</b> Actuation systems, Pneumatic and Hydraulic systems- constructional details of filter, lubricator, regulator, direction control valves, pressure control valves, flow control valves, actuators-linear and rotary.</p>	<b>CO1</b> <b>CO3</b>

	<b>ELECTRICAL ACTUATION SYSTEMS:</b> Electrical systems, Mechanical switches, solid state switches, solenoids, DC motors, AC motors, stepper motors. Characteristics of pneumatic, hydraulic, electrical actuators and their limitations.	
<b>UNIT-3</b>	<b>BASIC SYSTEM MODELS:</b> Mathematical models, mechanical system building blocks, electric system building blocks, fluid system building blocks, thermal system building blocks. <b>DYNAMIC RESPONSES OF SYSTEMS:</b> Transfer function, Modelling dynamic systems, first order and second order systems.	<b>CO1 CO4</b>
<b>UNIT-4</b>	<b>CLOSED LOOP CONTROLLERS:</b> Classification of control systems, feedback, closed loop and open loop systems, continuous and discrete processes, control modes, two step mode, proportional mode, derivative control, integral control, PID controller. <b>MICROPROCESSOR AND MICRO CONTROLLER:</b> Introduction, Architecture of a microprocessor (8085), Architecture of a Micro controller, Difference between microprocessor and a micro controller.	<b>CO1 CO5</b>
<b>UNIT-5</b>	<b>DIGITAL LOGIC:</b> Digital logic, number systems, logic gates, Boolean algebra, Karnaugh maps, application of logic gates, sequential logic, transducer Signal Conditioning and devices for data conversion. <b>PROGRAMMABLE LOGIC CONTROLLERS:</b> Introduction, basic structure, input/output processing, programming, mnemonics, timers, internal relays and counters, shift register, master and jump controls. Data handling, Analog input/output, selection of a PLC. <b>FUZZY LOGIC APPLICATIONS IN MECHATRONICS:</b> Fuzzy logic systems, Fuzzy control, Uses of Fuzzy expert systems.	<b>CO1 CO6</b>

### Learning Resources

<b>Text Books</b>	<ol style="list-style-type: none"> <li>1. Mechatronics Electronic Control Systems in Mechanical and Electrical Engineering, (3rd edition), by W Bolton, Pearson Education Press, 2005.</li> <li>2. Mechatronics System Design, 5<sup>th</sup> Indian reprint, 2009, by Devdas shetty, Richard A. kolk, PWS Publishing Company</li> </ol>
<b>Reference Books</b>	<ol style="list-style-type: none"> <li>1. Mechatronics Source Book, by Newton C Braga, Thomson Publications, Chennai.</li> <li>2. Mechatronics, by N. Shanmugam, Anuradha Agencies Publishers.</li> <li>3. Control sensors and actuators, by C.W.Desilva, Prentice Hall.</li> <li>4. Design with Microprocessors for Mechanical Engineers, by Stiffler, A.K.McGraw- Hill(1992).</li> </ol>
<b>E-Resources &amp; other digital material</b>	<ol style="list-style-type: none"> <li>1. <a href="https://onlinecourses.nptel.ac.in/noc22_me54/course">https://onlinecourses.nptel.ac.in/noc22_me54/course</a></li> </ol>

Commented [RK1]: