

ROBOTICS

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|--|------------------|---------------------------------|-------|----------------------|--------|
| Course code | 20ME2702B | Year | IV | Semester | I |
| Course category | Open Elective-IV | Branch | EEE | Course Type | Theory |
| Credits | 3 | L-T-P | 3-0-0 | Prerequisites | - |
| Continuous Internal Evaluation: | 30 | Semester End Evaluation: | 70 | Total Marks: | 100 |

| CO | Statement: The students will be able to | Skill | Blooms Level | Units |
|-----|--|--------------------------|--------------|-----------|
| CO1 | Understand the basic anatomy of robots, actuators, end effectors, robot sensors, programming and applications. | Understand | L2 | 1,2,3,4,5 |
| CO2 | Understand the working principles of robot actuators, end effectors | Understand | L2 | 2 |
| CO3 | Apply robot programming skills | Apply, Modern Tool Usage | L3 | 3 |
| CO4 | Apply knowledge of robot sensors and their applications in industries | Apply | L3 | 4,5 |

| Contribution of Course Outcomes towards achievement of Program Outcomes | | | | | | | | | | | | | | |
|---|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | | | | | | | | | | | | 3 | 1 |
| CO2 | 3 | 3 | | | | | | | | | | | 3 | 1 |
| CO3 | 3 | 3 | 2 | | 2 | | | | | | | | 3 | 1 |
| CO4 | 3 | | 2 | | | | | | | | | | 3 | 1 |

| Syllabus | |
|----------|---|
| Unit No | Contents |
| I | Introduction: Automation and robotics – History of robots -Robot anatomy – classification of robots, major components-robot specifications, selection of robots. |
| II | Robot actuators- Pneumatic, Hydraulic actuators, electric & stepper motors End Effectors- types of end effectors, grippers and tools, Requirements and challenges of end effectors. |
| III | Robot Programming: - Robot programming languages - programming methods - off and on-line programming - Lead through method - Teach pendent method, simple programs. |
| IV | Sensors used in robots: Sensor devices, Types of sensors - contact, position and displacement sensors, Force and torque sensors - Proximity and range sensors - acoustic sensors –slip sensors, Robot vision systems |
| V | Applications of robots: Application of robots in industry - material handling, processing operations, assembly, and inspection operations. |

Learning Resource

Text books:

1. Mikell P. Groover. Industrial Robotics Technology Programming and Applications, McGraw Hill Co., Singapore.
2. Robotic Engineering by Richard D.Klafter, Prentice Hall

Reference books

1. Introduction to Robotics – Saeed B.Niku, Prentice Hall
2. Introduction to Robotics – John J. Craig, Addison Wesley

E-Resources & other digital Material:

1. [1.http://nptel.ac.in/downloads/112101098/](http://nptel.ac.in/downloads/112101098/)